

DHOUT Versi on 22 Peter Lohmander 2010_08_11 1446

News:

This version (below) of the software should be OK for up to 25 time periods (years) and up to 8 different areas. It is OK in combination with the original "Qbasic" software.

Compare the complete example below!

It is also possible to obtain alternatives to the original "QBasic", for instance "PowerBASIC". With such alternatives, much larger problems should be possible to solve with practically the same code (as the code in this document).

Peter Lohmander

"DHIN Peter Lohmander 2010_08_10 Versi on 22"
1 "Less"
8 "kmax"
25 "tmax"
.05 "rate"
50 "p"
40 "concos"
100 "z1"
150 "z2"
210 "z3"
160 "z4"
150 "z5"
140 "z6"
220 "z7"
230 "z8"
2000 "c1"
3500 "c2"
4900 "c3"
5500 "c4"
5700 "c5"
5900 "c6"

6200 "c7"
6700 "c8"
0 "cc11"
1800 "cc12"
3700 "cc13"
4100 "cc14"
4200 "cc15"
4300 "cc16"
4400 "cc17"
4800 "cc18"
1800 "cc21"
0 "cc22"
3700 "cc23"
4100 "cc24"
4200 "cc25"
4300 "cc26"
4400 "cc27"
4800 "cc28"
1900 "cc31"
1800 "cc32"
0 "cc33"
4100 "cc34"
4200 "cc35"
4300 "cc36"
4400 "cc37"
4800 "cc38"
2100 "cc41"
1800 "cc42"
3700 "cc43"
0 "cc44"
4200 "cc45"
4300 "cc46"
4400 "cc47"
4800 "cc48"
2200 "cc51"
1800 "cc52"
3700 "cc53"
4100 "cc54"
0 "cc55"
4300 "cc56"
4400 "cc57"
4800 "cc58"
2800 "cc61"
1800 "cc62"
3700 "cc63"
4100 "cc64"
4200 "cc65"
0 "cc66"
4400 "cc67"
4800 "cc68"
3200 "cc71"
1800 "cc72"
3700 "cc73"
4100 "cc74"
4200 "cc75"
4300 "cc76"
0 "cc77"
4800 "cc78"
3400 "cc81"
1800 "cc82"
3700 "cc83"
4100 "cc84"
4200 "cc85"
4300 "cc86"

OPTIMAL RESULTS FROM DHI NV
 Software by
 Peter Lohmander 2010

OPTIMAL TIME AND STATE DEPENDENT DECISIONS AND EXPECTED PRESENT
 VALUES

t = 1
 i (t) E(PV) i (t+1) DEC CVIA Entering Partial States

 1 649538. 33 3 0 0 0 0 0 0 0 0 0

t = 2
 i (t) E(PV) i (t+1) DEC CVIA Entering Partial States

 33 662190. 34 8 3 0 0 1 0 0 0 0 0

t = 3
 i (t) E(PV) i (t+1) DEC CVIA Entering Partial States

 34 664361. 36 7 3 0 0 1 0 0 0 0 1

t = 4
 i (t) E(PV) i (t+1) DEC CVIA Entering Partial States

 36 656185. 100 2 0 0 0 1 0 0 0 1 1

t = 5
 i (t) E(PV) i (t+1) DEC CVIA Entering Partial States

 100 636945. 116 4 2 0 1 1 0 0 0 1 1

t = 6
 i (t) E(PV) i (t+1) DEC CVIA Entering Partial States

 116 611789. 124 5 2 0 1 1 1 0 0 1 1

t = 7
 i (t) E(PV) i (t+1) DEC CVIA Entering Partial States

 124 581638. 128 6 2 0 1 1 1 1 0 1 1

t = 8
 i (t) E(PV) i (t+1) DEC CVIA Entering Partial States

 128 547390. 256 1 2 0 1 1 1 1 1 1 1

t = 9
 i (t) E(PV) i (t+1) DEC CVIA Entering Partial States

 256 509048. 256 1 1 1 1 1 1 1 1 1

t = 10
 i (t) E(PV) i (t+1) DEC CVIA Entering Partial States

 256 465689. 256 1 1 1 1 1 1 1 1 1

t = 11

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$i(t)$	E(PV)	$i(t+1)$	DEC	CVIA	Entering	Partial	States
256	424445.	256			1	1	1

t = 12

$i(t)$	E(PV)	$i(t+1)$	DEC	CVIA	Entering	Partial	States
256	385212.	256			1	1	1

t = 13

$i(t)$	E(PV)	$i(t+1)$	DEC	CVIA	Entering	Partial	States
256	347893.	256			1	1	1

t = 14

$i(t)$	E(PV)	$i(t+1)$	DEC	CVIA	Entering	Partial	States
256	312394.	256			1	1	1

t = 15

$i(t)$	E(PV)	$i(t+1)$	DEC	CVIA	Entering	Partial	States
256	278626.	256			1	1	1

t = 16

$i(t)$	E(PV)	$i(t+1)$	DEC	CVIA	Entering	Partial	States
256	246505.	256			1	1	1

t = 17

$i(t)$	E(PV)	$i(t+1)$	DEC	CVIA	Entering	Partial	States
256	215951.	256			1	1	1

t = 18

$i(t)$	E(PV)	$i(t+1)$	DEC	CVIA	Entering	Partial	States
256	186887.	256			1	1	1

t = 19

$i(t)$	E(PV)	$i(t+1)$	DEC	CVIA	Entering	Partial	States
256	159240.	256			1	1	1

t = 20

$i(t)$	E(PV)	$i(t+1)$	DEC	CVIA	Entering	Partial	States
256	132942.	256			1	1	1

t = 21

$i(t)$	E(PV)	$i(t+1)$	DEC	CVIA	Entering	Partial	States
256	107926.	256			1	1	1

t = 22

$i(t)$	E(PV)	$i(t+1)$	DEC	CVIA	Entering	Partial	States
256	84130.	256			1	1	1

t = 23

$i(t)$	E(PV)	$i(t+1)$	DEC	CVIA	Entering	Partial	States
256	61495.	256			1	1	1

t = 24	i(t)	E(PV)	i(t+1)	DEC	CVIA	Entering	Partial	States
256	39964.	256				1	1	1

t = 25	i(t)	E(PV)	i(t+1)	DEC	CVIA	Entering	Partial	States
256	19482.	256				1	1	1

SOFTWARE

REM
REM DHI nv22
REM Peter Lohmander
REM 2010_08_11_1437
CLS

OPEN "DHOut.txt" FOR OUTPUT AS #1
OPEN "DHIN.txt" FOR INPUT AS #2

DIM W(256, 26), M(8, 256), z(8), c(8, 256)
DIM cc(8, 8), MEX(10)
DIM jopt(256, 26), cvia(8, 256)

INPUT #2, Info\$
INPUT #2, Less, a\$
INPUT #2, kmax, a\$
INPUT #2, tmax, a\$
INPUT #2, rate, a\$
INPUT #2, p, a\$
INPUT #2, concos, a\$

i max = 2 ^ kmax
j max = i max

FOR k = 1 TO kmax
INPUT #2, z(k), a\$
NEXT k

REM
REM ***** Connecti on Costs vi a the Pri mary Source *****
REM
FOR k = 1 TO kmax
INPUT #2, c(k, 1), a\$
c(k, 1) = c(k, 1) + concos * z(k)
NEXT k

REM
REM ***** Costs of connecting one area vi a another area *****
REM
FOR k = 1 TO kmax
FOR M = 1 TO kmax
INPUT #2, cc(k, M), a\$
NEXT M
NEXT k

FOR k1 = 1 TO kmax
FOR k2 = 1 TO kmax
IF k2 = k1 THEN GOTO 444

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cc(k1, k2) = cc(k1, k2) + concos * z(k1)
444 REM
NEXT k2
NEXT k1

PRINT #1, ""
PRINT #1, "OPTIMAL RESULTS FROM DHI NV"
PRINT #1, "Software by "
PRINT #1, "Peter Lohmander 2010"
REM PRINT #1, ""
REM PRINT #1, "tmax = ", tmax, " kmax = ", kmax, " imax = jmax = ";
imax

REM
REM ***** Terminal conditions *****
REM
FOR i = 1 TO imax
W(i, (tmax + 1)) = 0
NEXT i

REM
REM ***** Calculation of the membership function *****
REM
mnum = 0
FOR k = kmax TO 1 STEP -1
value = 0
mnum = mnum + 1
mm = 2 ^ (mnum - 1)
count = 0
FOR i = 1 TO imax
count = count + 1
M(k, i) = value
change = 0
IF count = mm THEN change = 1
IF change = 1 THEN count = 0
chdown = 0
IF value = 1 THEN chdown = 1
chup = 0
IF value = 0 THEN chup = 1
IF (change = 1 AND chdown = 1) THEN value = 0
IF (change = 1 AND chup = 1) THEN value = 1
NEXT i
NEXT k

REM
REM ***** Calculation of State Dependent Partial *****
REM ***** Investment Cost Functions *****
REM
FOR i = 2 TO imax
FOR k = 1 TO kmax
IF M(k, i) = 1 THEN c(k, i) = 0
IF M(k, i) = 1 THEN GOTO 222
c(k, i) = c(k, 1)
FOR kconnect = 1 TO kmax
IF M(kconnect, i) = 0 THEN GOTO 333
IF kconnect = k THEN GOTO 333
clock = cc(k, kconnect)
IF clock < c(k, i) THEN cvia(k, i) = kconnect
IF clock < c(k, i) THEN c(k, i) = clock
333 REM
NEXT kconnect

```

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222 REM
    NEXT k
NEXT i

```

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REM
REM ***** Dynamic Programming via Backward Recursion *****
REM
FOR t = tmax TO 1 STEP -1
    d = EXP(-rate * t)
    FOR i = 1 TO imax
        optF = -999999
        optJ = 0
        FOR j = 1 TO jmax
            neginv = 0
            numinv = 0
            FOR k = 1 TO kmax
                IF (M(k, j) - M(k, i)) = 1 THEN numinv = numinv + 1
                IF (M(k, j) - M(k, i)) < 0 THEN neginv = neginv + 1
            NEXT k
            IF neginv > 0 THEN GOTO 100
            IF numinv > 1 THEN GOTO 100
            net = 0
            FOR k = 1 TO kmax
                net = net + p * M(k, i) * z(k)
            NEXT k
            FOR k = 1 TO kmax
                IF (M(k, j) - M(k, i)) = 1 THEN net = net - c(k, i)
            NEXT k
            F = d * net + W(j, (t + 1))
            IF F > optF THEN optJ = j
            IF F > optF THEN optF = F
100 REM
            NEXT j
        W(i, t) = optF
    REM PRINT #1, "t = "; t; " i = "; i; " optF = "; optF; " optJ = ";
    optJ
    jopt(i, t) = optJ
    NEXT i
NEXT t

```

```

PRINT #1, ""
PRINT #1, "OPTIMAL TIME AND STATE DEPENDENT DECISIONS AND EXPECTED
PRESENT VALUES"
instate = 1
FOR t = 1 TO tmax
    PRINT #1, ""
    PRINT #1, " t = ";
    PRINT #1, USING "###"; t

    PRINT #1, " i(t) E(PV) i(t+1) DEC CVIA Entering Partial
States"
    PRINT #1, "
-----"
    FOR i = 1 TO imax

    IF (i < instate OR i > instate) AND (Less = 1) THEN GOTO 888

    FOR k = 1 TO kmax
        MEX(k) = M(k, i)
    NEXT k

```

```

PRINT #1, USING "####"; i;
PRINT #1, USING "#####. "; W(i, t);

invnumb = 0
FOR k = 1 TO kmax
IF (M(k, jopt(i, t)) - M(k, i)) > 0 THEN invnumb = k
NEXT k
PRINT #1, USING "####"; jopt(i, t);
PRINT #1, " ";

IF invnumb > 0 THEN PRINT #1, USING "###"; invnumb;
IF invnumb = 0 THEN PRINT #1, " ";

IF invnumb > 0 THEN PRINT #1, USING "#####"; cvi a(invnumb, i);
IF invnumb = 0 THEN PRINT #1, " ";

PRINT #1, " ";
FOR k = 1 TO kmax
PRINT #1, USING "##"; MEX(k);
NEXT k
PRINT #1, ""

888 REM

NEXT i
instate = jopt(instate, t)

NEXT t

CLOSE #1
CLOSE #2

END

```